ION Alberta Chapter



THE REAL-TIME

CANADA-WIDE DGPS SERVICE

LE SERVICE DGPS

PAN-CANADIEN EN TEMPS RÉEL

Calgary, Alberta

Overview



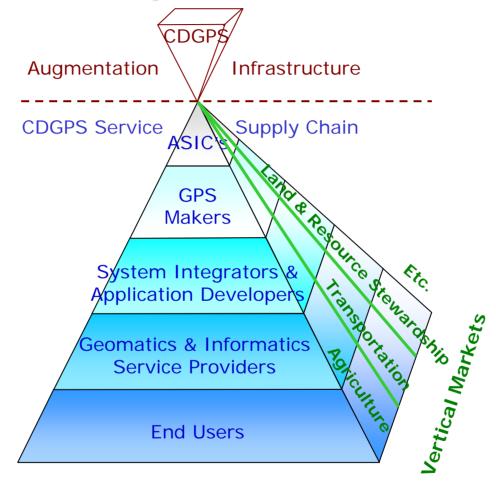
THE REAL-TIME

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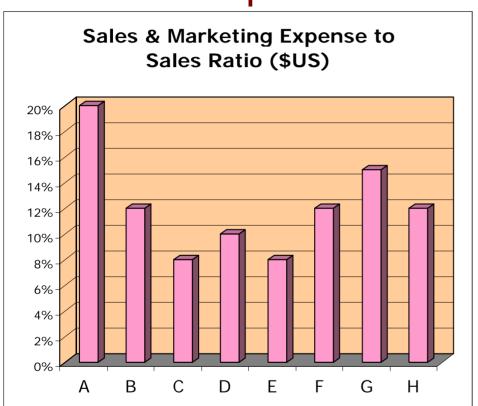
PAN-CANADIEN EN TEMPS RÉEL

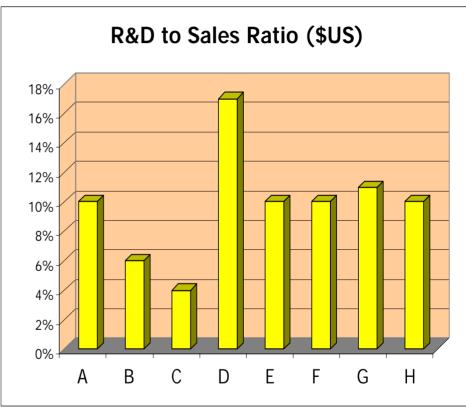
National GNSS Augmentation Infrastructure





GPS Manufacturing Industry Expense: Sales Thumbnails









Augmentation Service Comparison (2004)

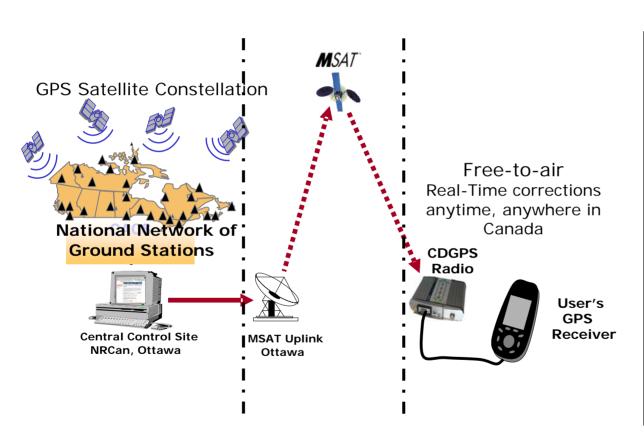
		CDGPS	Coast Guard	WAAS
Performance	Accuracy	0.5-2m	1-2m	1-2m
	Reference Frame	NAD83	NAD83	WGS84
Coverage	Foliage	fair	good	poor
	Coastal North	good	fair	poor
	Inland North	good		poor
	Coastal South	good	good	good
	Inland South	good		good
	Urban	fair	good	fair
Cost	Service	free	free	free
	DGPS Radio		\$300	
	Generic Combo	\$1,500	\$1,000	\$300
	Quality Combo	\$4,000		
Backing	Resourced	modest	significant	significant
	Track Record	new	established	evolving

Hardy Carter Strategic Analysis and Issues, CDGPS Source:



Canada-wide Differential GPS (CDGPS)

A Space-Based Augmentation System



Canadian Council on Geomatics

- Federal Govt Geomatics interests from NRCan, DND, DFO, StatsCan
- Govt Geomatics agencies of all 10 provinces and 3 territories
- \$2.3M to develop 1999 to 2003
- \$1.6M to operate 2003 to 2007
- \$400K to operate annually until 2010



Funding Source 2000-2007

Cost savings realized by purchasing MSAT carriage under PWGSC's discount		\$2,888,000	
Federal	GeoConnections	\$600,000	19%
Government	Canadian Hydrographic Service	\$100,000	3%
Provinces and Territories		\$2,525,000	78%
CCOG Total Investment		\$3,225,000	100%

Development of satellite hub and 1000 MSAT radios ~\$2.3M from Apr, 2000 to Oct, 2003

Annual Operation

 (mostly non-subsidized portion of carriage cost)
 ~\$1.6M for 3.5 yrs of operation from Oct, 2003 to Mar, 2007



SCOG Cash Contribution

Current Operations



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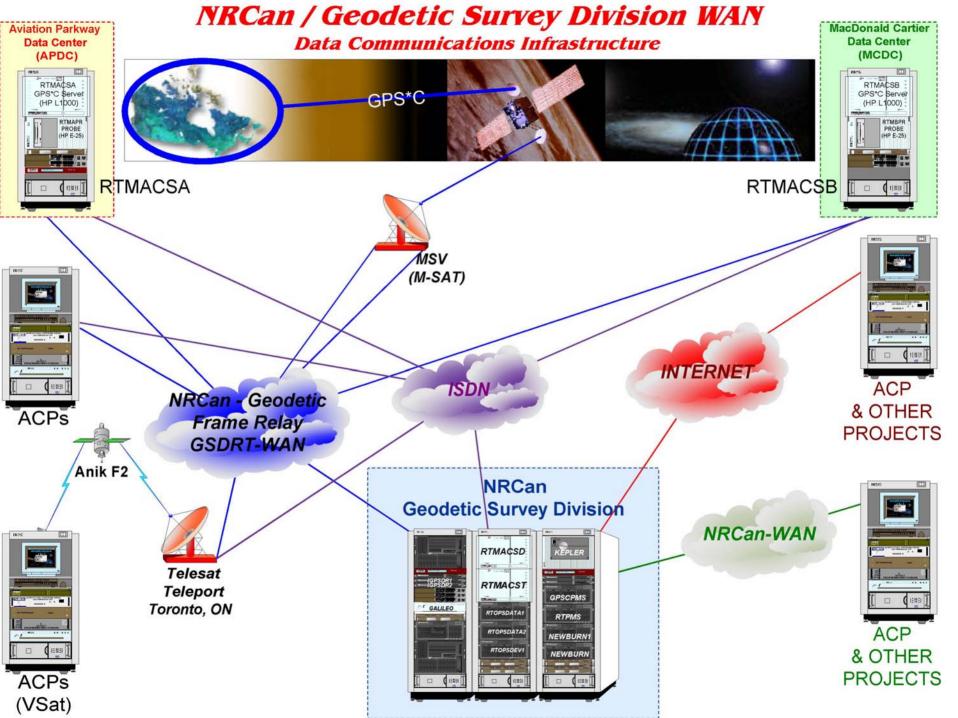
CDGPS Corrections

History of GPS-C Development

- The GPS-C Prototype was designed and developed in 1995-1996
- The GPS-C Prototype was further enhanced during the period 1997-2002
 - Network expansion
 - Refining the GPS-C engine
 - Architecture for high availability service finalized
 - Service management and monitoring requirements identified
 - Service agreements with service levels signed





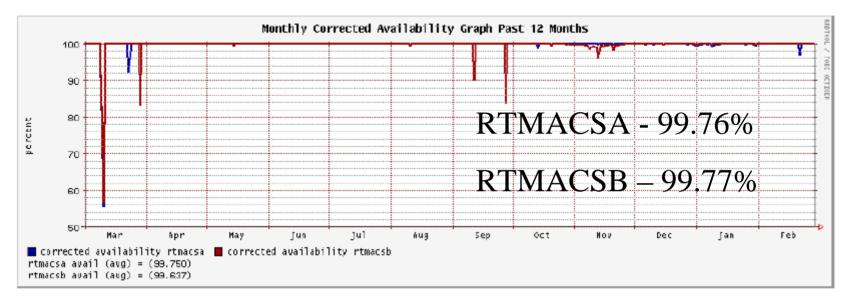


Tasks in Delivering GPS-C

- Daily operations at NRCan
 - Performance monitoring (availability and accuracy)
 - Helpdesk 8x5
 - 24/7 application support
 - Change management
- Engineering support at NRCan
 - Performance feedback to operations
 - Bug fixes
 - Inputs to post mortems
- Monthly Reporting
 - To CDGPS since October 2002



Availability of the GPS-C Service Mar 06 – Feb 07



- March 2006 first and only service outage since service began in 2002
- Service outage == both production servers down at the same time



The GPS Correction Model

 $\left(GPS\cdot C\right)$ NRCan's Ultra Rapid Predictions (hourly)



Real-Time GPS Tracking (RT-Canadian Active Control System)



GPS·**C** Application



MRTCA Messages

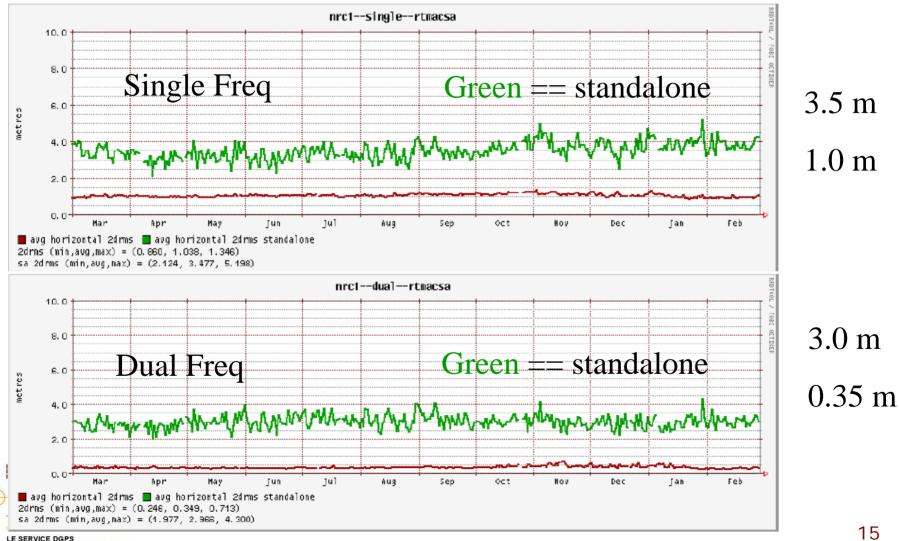


See ICD for details





2drms Service Performance in Red NRC1 Mar 06 - Feb 07



PAN-CANADIEN EN TEMPS RÉEL

Current Operations



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Broadcast Service

CDGPS Broadcast Service Overview

- How we arrived at where we are
- Present status:
 - RT-CACS Infrastructure
 - CDGPS Hub Infrastructure
 - CDGPS radios localization
 - Developer tools engineering support
 - End user support help desk



Service Principles

- Free public infrastructure of real-time GPS corrections (GPS•C) via MSAT
- develop an initial portable user radio/receiver to 'seed' market
 - manufacturing, distribution and inventory management are outside of core competency
- create enabling environment for private sector adoption of the infrastructure



CDGPS Timeline

- Service proposed in 1999 Canadian Council on Geomatics resolution → MoA
- Participants: <u>all</u> provinces, Nunavut and the federal governments
- The Long & Winding Road ...
 - Start-up January 2000
 - CDGPS Service contractor hired October 2000
 - Marketing strategy (Hardy Report) January 2002
 - Pre-Alpha testing August 2002
 - Alpha testing October 2002 April 2003
 - Beta testing June-November 2003
 - Launched October 14, 2004
 - MOA Extension for an additional two years
 - Operational to March 31, 2007
 - MOA Extension for an additional three years
 - Operational to March 31, 2010



Challenges

- Leading Edge Technical Solution
- USA announcement on SA
- Initial trouble attracting contractor/builder
- Over-optimistic prime contractor
- MSAT-1 failure
- Extended schedules
- Limited budget
- Commercial service standards
- Distribution channel, marketing
- Initial inventory of CDGPS receivers sold out within 15 months
 - leaving only 1 supplier of equipment capable of accessing CDGPS



CDGPS Deliverables

- NRCan's RT-CACS Infrastructure
- CDGPS Infrastructure
- CDGPS radio
- Documentation
- Distribution and marketing
- Developers Tool Kit
- Business studies and documentation



RT-CACS Infrastructure

- NRCan RT-CACS Network → GPS*C data source
- General Information ...
 - GPS*C operational and in production mode as of Nov. 4, 2002
 - GPS*C operations are under Service Level Agreement (SLA) with PWGSC/GTIS
 - The RT-MACS facilities are fully redundant
 - Full Integrity Monitoring available online
 - Monthly reporting to CDGPS office

Performance

- Accuracy: Typically meeting 1.5m @ 95%*
- Availability: Redundant Hub has covered any large outages
 - No major problems/issues



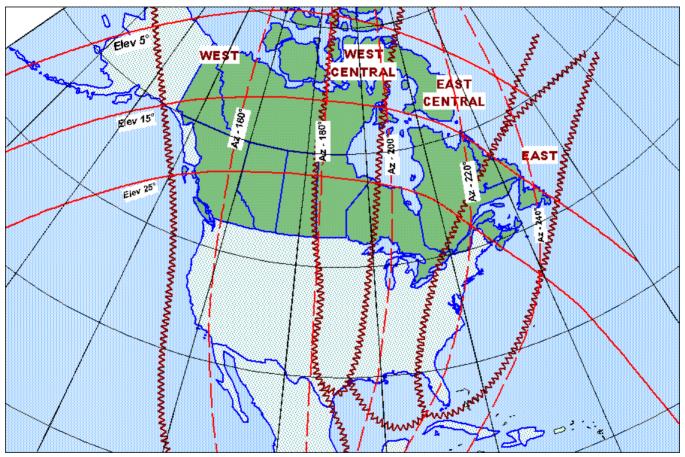
* with suitable hardware & operating condition

CDGPS Hub Infrastructure

- Main components:
 - CDGPS Hub + MSAT + CDGPS radio + RMS
 - CDGPS Service Center / Provider (BMGS)
- Key Performances
 - Fully redundant system that accepts separate data feeds from the NRCan RT-MAC's
 - Manned 24/7 and is powered by generator backed UPS systems
 - Monthly reporting & detailed system logs
- Operation & Maintenance Contract → MSV
- Performance
 - No major problems/issues
 - Redundant hub has covered any outages

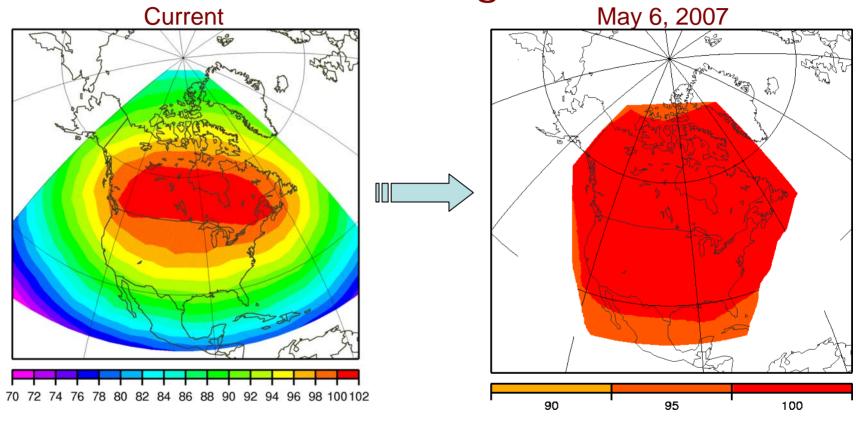


MSAT Coverage for CDGPS Broadcast





CDGPS Corrections – North American Coverage

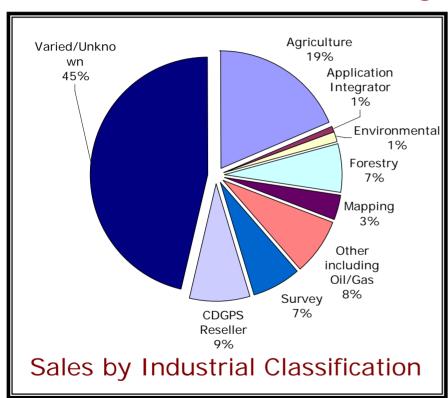


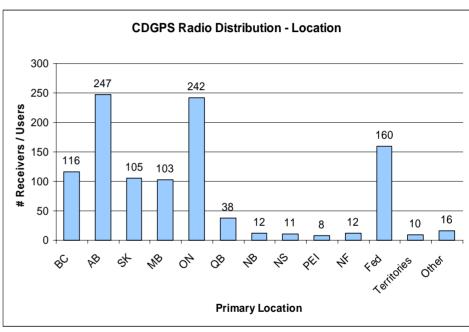


percentage of GPS satellites which will have CDGPS corrections among the total list of GPS satellites in view above 10° elevation

CDGPS Radio Sales

(no longer in supply)





Sales by Geographic Location



Summary

- Commercial Operation
 - Operational for 3.5 years
 - Six (6) Resellers Established for Canada
- Industry acceptance for CDGPS radio
 - based on CDGPS radio sales
- Industry support for CDGPS Service
 - based on NovAtel commercial product; Raven; Sokkia
- Government support for CDGPS Service
 - extension of CDGPS Service funding to March 2010



New Opportunities



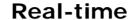
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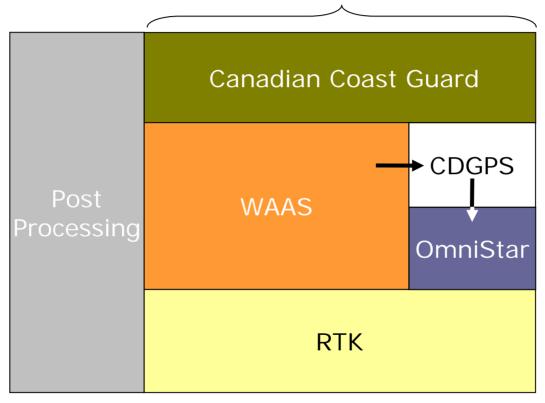
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CDGPS: Market Context

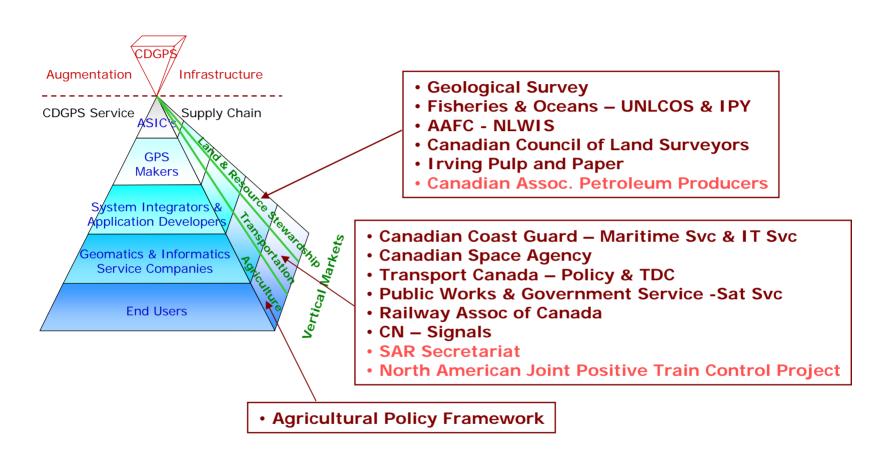




Source: CDGPS Strategic Analysis and Issues, Carter & Hardy



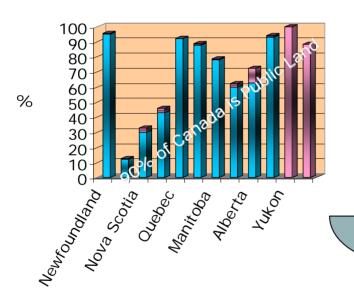
Target Areas





Land & Resource Stewardship on Public Lands in Canada

Proportion of Public Land in Each Province & Territory



National Accuracy Standards for Integrated Surveys CCOG Resolution S05-10

Location	Accuracy (95%)	
Urban Areas	5 cm	
Rural Areas	20 cm	
Remote Areas	1 m	

■ Provincial Crown Land ■ Federal Crown Land



GNSS Augmentation Infrastructure

'Conceptually-speaking' Localized High Accuracy Services



Future Opportunities

- North America-wide extension
 - greater incentive for private sector value-add
- CDGPS Service adoption
 - increased industry participation
 - possible funding opportunities
 - CDGPS Service resources for infrastructure, operation & maintenance
- Dual-Frequency users
 - directly demodulate MSAT signal
 - expect 20-30 cm (95 %) positioning
- Extend governance to include more private sector and research organizations' participation
- Internet / Alternate services (beyond MSAT)



Three Defining Features of CDGPS

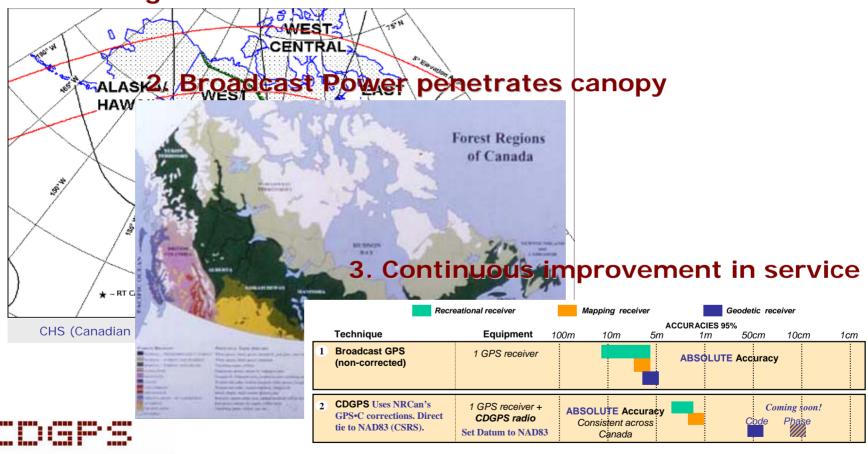
1. Coverage to Ellesmere Island

THE REAL-TIME

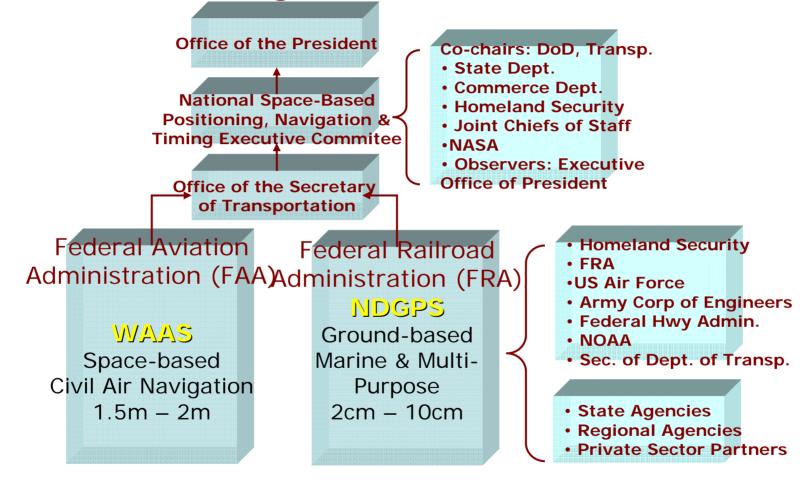
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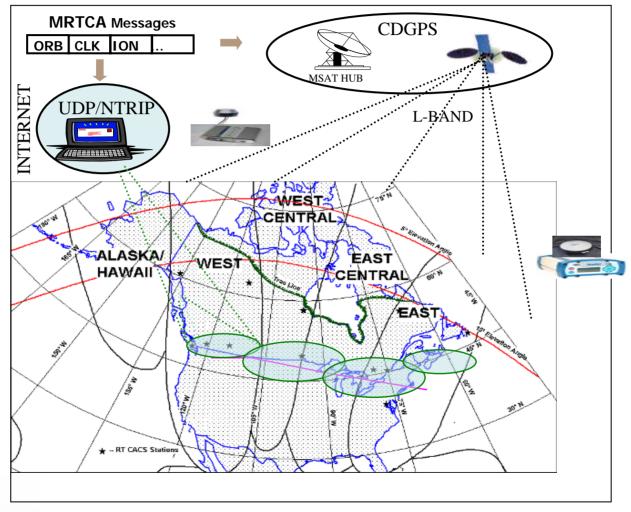


US GNSS Augmentation Infrastructure





GPS-C Distribution Channels





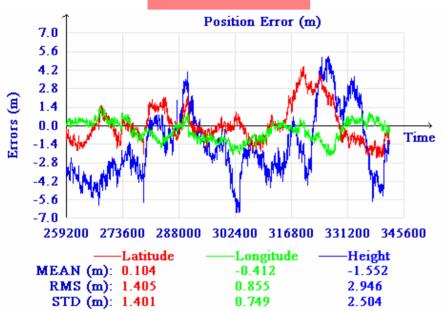
GPS-C NTRIP Server Features

- A Java application that runs under Linux/Windows
- Developed and tested under contract by Golden Sun Inc. in cooperation with the University of Calgary.
- Acquires MRTCA messages from a GPS-C UDP Server or a CDGPS radio serial port.
- Forwards a single MRTCA and/or multiple RTCM correction sources (computed by localizing the widearea corrections for user-defined locations) to an NTRIP Caster.
- Is administered using a Web-based interface.

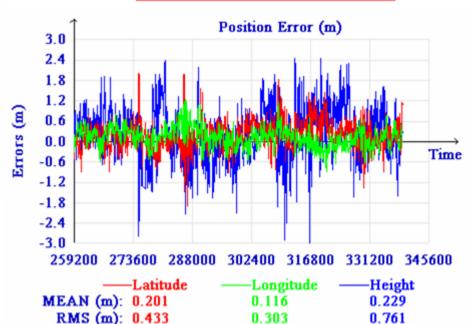


GPS-C NTRIP DGPS Performance





iRelay DGPS



0.280





STD (m): 0.383

0.726