Antenna Phase Center Variation in Multipath Environment



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Phase Center – where it matters?

- Ranging applications (positioning, attitude, surveying, etc.)
- Imaging applications (radio-telescope, image radars)
- Antenna array applications (i.e. null steering)
- UWB (signal cohesion and group delay distortion)



IEEE Standard Phase Centre Definition

The location of a point associated with an antenna such that, if it is taken as the center of a sphere whose radius extends into the farfield, the phase of a given field component over the surface of the radiation sphere is "essentially" constant, at least over the portion of the surface where the radiation is significant.

Notes: Some antennas do not have a unique phase center.

Far-Field condition: $\Delta \psi \le 22.5^{\circ} \Longrightarrow (\lambda_{o}/8)$

Source: Antenna Standards Committee of the IEEE Antennas and Propagation Group



Phase Center Measurements Methods

- Second Derivative Method [1]
- Two Point Method [2]
- Edge Diffraction Method [3]
- Differential Phase Method [4]
- Three Antenna Method [5]
- Intuitive for "dummies" Method (this presentation)
- Time of Arrival (TOA) Method [6]



Phase Center Model



Fig. 1: Antenna model (according to Zeimetz and Kuhlmann 2006).

 e_0 - is the unit vector of satellite obse₀ - is the unit vector of satellite observation (From sat. to PCO),

r - is the radius of perfect phase sphere originating at E

Correction Function:
$$S_{ARP} = r + PCO \cdot e_0 + PCV(\alpha, \beta) + \varepsilon$$
 (1)

PCO is found by minimizing the cost function:

 $\sum (PCV)^2 = Min$



Phase Center Determination

$$Phase(\phi, \theta) = \frac{2\pi}{\lambda} (x \cdot \cos \phi \sin \theta + y \cdot \sin \phi \sin \theta + z \cdot \cos \theta) + d$$

or in matrix form:

$$F(\phi,\theta) = \frac{2\pi}{\lambda} \left[\cos\phi\sin\theta \quad \sin\phi\sin\theta \quad \cos\theta \quad 1 \right] \cdot \begin{vmatrix} x \\ y \\ z \\ d' \end{vmatrix} \implies F = M \cdot P \quad (1)$$



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To find phase center P we use eq. (1), hence: $P = M^{-1} \cdot F$ $\begin{bmatrix} x \\ y \\ z \\ d' \end{bmatrix} = \frac{\lambda}{2\pi} [\cos \phi \sin \theta \quad \sin \phi \sin \theta \quad \cos \theta \quad 1]^{-1} \cdot F(\phi, \theta)$

Assemble solution matrix

$$\begin{bmatrix} x^{1} & x^{2} & : & x^{L} \\ y^{1} & y^{2} & : & y^{L} \\ z^{1} & y^{2} & : & y^{L} \\ d^{1} & d^{2} & : & d^{L} \end{bmatrix} = \frac{1}{2\pi} \bullet \begin{bmatrix} \cos \phi_{1} \sin \theta_{1} & \sin \phi_{1} \sin \theta_{1} & \cos \theta_{1} & 1 \\ \cos \phi_{2} \sin \theta_{1} & \sin \phi_{2} \sin \theta_{1} & \cos \theta_{1} & 1 \\ \vdots & \vdots & \vdots & \vdots \\ \cos \phi_{N} \sin \theta_{1} & \sin \phi_{N} \sin \theta_{1} & \cos \theta_{1} & 1 \\ \cos \phi_{1} \sin \theta_{2} & \sin \phi_{1} \sin \theta_{2} & \cos \theta_{1} & 1 \\ \vdots & \vdots & \vdots & \vdots \\ \cos \phi_{N} \sin \theta_{K} & \sin \phi_{N} \sin \theta_{K} & \cos \theta_{K} & 1 \end{bmatrix}^{-1} \bullet \begin{bmatrix} \varphi_{1}^{1}(\phi_{1}, \theta_{1}) \cdot \lambda^{1} & \varphi_{1}^{2}(\phi_{1}, \theta_{1}) \cdot \lambda^{2} & : & \varphi_{1}^{L}(\phi_{2}, \theta_{1}) \cdot \lambda^{L} \\ \varphi_{2}^{1}(\phi_{2}, \theta_{1}) \cdot \lambda^{1} & \varphi_{1}^{2}(\phi_{N}, \theta_{1}) \cdot \lambda^{2} & : & \varphi_{1}^{L}(\phi_{N}, \theta_{1}) \cdot \lambda^{L} \\ \vdots & \vdots & \vdots & \vdots \\ \varphi_{N}^{1}(\phi_{N}, \theta_{1}) \cdot \lambda^{1} & \varphi_{1}^{2}(\phi_{N}, \theta_{1}) \cdot \lambda^{2} & : & \varphi_{1}^{L}(\phi_{N}, \theta_{1}) \cdot \lambda^{L} \\ \varphi_{N+1}^{1}(\phi_{1}, \theta_{2}) \cdot \lambda^{1} & \varphi_{N+1}^{2}(\phi_{N}, \theta_{1}) \cdot \lambda^{2} & : & \varphi_{N+1}^{L}(\phi_{1}, \theta_{2}) \cdot \lambda^{L} \\ \vdots & \vdots & \vdots & \vdots \\ \varphi_{N+1}^{1}(\phi_{1}, \theta_{2}) \cdot \lambda^{1} & \varphi_{N+1}^{2}(\phi_{N}, \theta_{N}) \cdot \lambda^{2} & : & \varphi_{N+1}^{L}(\phi_{1}, \theta_{2}) \cdot \lambda^{L} \\ \vdots & \vdots & \vdots & \vdots \\ \varphi_{N+K}^{1}(\phi_{N}, \theta_{K}) \cdot \lambda^{1} & \varphi_{N+K}^{2}(\phi_{N}, \theta_{K}) \cdot \lambda^{2} & : & \varphi_{N+K}^{L}(\phi_{N}, \theta_{K}) \cdot \lambda^{L} \end{bmatrix}$$

where:
$$\varphi_i = 0: \frac{2\pi}{N}: 2\pi, \quad \theta_i = 0: \frac{\pi}{2K}: \frac{\pi}{2}$$
 (upper hemisphere)
or: $\varphi_i = -\frac{\pi}{2}: \frac{\pi}{N}: \frac{\pi}{2}, \quad \theta_i = -\frac{\pi}{2}: \frac{\pi}{K}: \frac{\pi}{2}$ (upper hemisphere)

L: Number of frequencies



Ideal Phase Patterns



Ideal Phase Pattern shifted along Z-axis from origin (0,0,0) to (0,0,1)



Shifted Ideal Phase Patterns



Ideal Phase Pattern shifted along X-axis from origin (0,0,0) to (1,0,0)



Precise thinking

Ideal Phase Pattern shifted along Y-axis from origin (0,0,0) to (0,1,0)

Shifted Ideal Phase Patterns



Ideal Phase Pattern shifted along X,Y,Z-axis from origin (0,0,0) to (1,1,2)



Step 1 – Determine PCO



Measured phase pattern of AR25 antenna (note that this phase pattern shape is heavily weighted by large Z-axis offset of yet to be determined PCO value)



Step 2 – Determine ideal spherical phase pattern at determined PCO location





Step 3 – Determine PCV



Computed PCV around PCO:



Nov Ate

In

Example 1 – Anechoic chamber measurements versus Geo++ live GPS signal measurements









Horizontal Phase Center of SGH Antenna



Precise thinking

Nr

Radiation Amplitude Patterns (GNSS and SGH Antenna)







PCO movement in Z-axis (SGH antenna)



Example 2 - Tightly coupled Array antenna





X Offset in mm



2-Ray Multipath Model using single reflector



Multipath Effect on PCO (Example of antenna with good multipath performance)











proto antenna in mixed ground, h=5m(wet and dry sand, concrete, PEC): Elevation Masking Angle between 20 and 0 deg

$$\hat{S}(\varphi,\theta) = \hat{C}^*(\varphi,\theta) \cdot \hat{E} + \hat{C}^*(\varphi,-\theta) \cdot \Gamma \cdot \hat{E} \cdot e^{j2\pi d/\lambda}$$

.

where:
$$\hat{E} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -j \end{pmatrix}$$
; $\hat{C}^*(\varphi, \theta) = \frac{a_{\phi,\theta}}{\sqrt{2}} \begin{pmatrix} 1 & j \end{pmatrix} e^{j\varphi(\phi,\theta)}$
 $\Gamma = \begin{bmatrix} \Gamma^{TE} & 0 \\ 0 & \Gamma^{TM} \end{bmatrix}$; $\hat{C}^*(\varphi, -\theta) = \frac{a_{\phi,-\theta}}{\sqrt{2}} \begin{pmatrix} 1 & \pm j \end{pmatrix} e^{j\varphi(\phi,-\theta)}$ $d = 2 \cdot h \sin(\theta)$

$$\hat{S}^{RHCP} = \frac{a_{R(\theta)}e^{j\delta(\theta)}}{\sqrt{2}} \begin{bmatrix} 1 & j \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -j \end{bmatrix}$$
$$\hat{S}^{LHCP} = \frac{a_{L(\theta)}e^{j\xi(\theta)}}{\sqrt{2}} \begin{bmatrix} 1 & -j \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -j \end{bmatrix}$$











Scaling Correction $(\phi, \theta) = \frac{a_{R(-\theta)}e^{j[\delta(-\theta)-\xi(-\theta)]}}{a_{L(-\theta)}}$



Conclusions & Final Remarks

- A simple method to determine Phase Center Offset/Location based on Least Square Method is described
- PCO can be very sensitive to near-by reflections surrounding an antenna
- Proper pattern control and controlling amount of x-pol is crucial to keep PCO stable
- Multipath mitigation can be employed using information received from well designed dual polarized antenna



References

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